

Bandwidth and energy efficient transmission in underwater Acoustic sensor network

Gunna Manoj Kumar¹ and S.VidyasagarAppaji²

¹Computer Science and Engineering (CNIS), Maharaj Vijayaram Gajapati Raj College of Engineering, Vizianagaram, Andhara Pradesh, India

²Computer Science and Engineering (Assistant Professor), Maharaj Vijayaram Gajapati Raj College of Engineering, Vizianagaram, Andhara Pradesh, India

Abstract

Most protocols used in physical wireless communication cannot be straightly applied in the underwater world. Underwater Acoustic Sensor Grid (UW-ASNs) accommodates procedure with sensing, processing, and communications capability that are deployed underwater to perform mutual monitoring tasks to support a large range of applications. The enabling communications technology for range over 100 meters is wireless acoustic interconnections due to the high reduction and distribution affecting radio and optical waves, respectively. In the Present effort, the difficulty of data gathering is carried by considering the communications between the routing functions and the characters of the underwater acoustic approach. In this paper, we focus on the Bandwidth and power efficient transmission in underwater Acoustic sensor grid, here we proposed two distributed environmental routing algorithms for hold up insensitive and hold up-sensitive.

I. INTRODUCTION

As supports for broad vary of applications, detector devices capable of sensing, processing, data acquisition, and communication are arranged under water [1], [2], so as to support applications for oceanographic knowledge assortment, ocean sampling, pollution and environmental observation, disaster interference. There is a need to enable capable communication protocols among underwater devices, to create underwater applications available. Due to the high reduction and distribution affecting radio and optical waves, severally, these devices area unit supported acoustic wireless technology for range over 100 meters, and the unique characters of the underwater acoustic communication control, such as classified bandwidth facility[1], and propagation hold ups[2], require new capable and reliable data communication protocols.

In our current effort, 2 information measure and power capable distributed environmental routing algorithms area unit being designed. These algorithms area unit designed

to satisfy the wants of hold up insensitive and hold up sensitive static underwater detector interconnections applications. The designed routing results are tailored for the characters of the 3D underwater environment. Once utilize communication protocols not particularly designed for this environment, these characters lead to a very low consumption of the underwater acoustic approach. Our routing clarifications allow achieving two inconsistent straights, i.e., 1) increasing the power of the acoustic approach and 2) restrictive the envelope error rate on each link. particularly the designed routing algorithms enable every node to put together choose its next hope, the optical put on air power and also the forward error correction (FEC) rate of each envelope, with the straights of minimizing the power consumption. FEC methods once control writing is achieve by calibration the number of FEC being without a job according to the dynamic approach conditions.

II. BACKGROUND WORK

An exhaustive study in routing protocols for physical wireless unintentional [3] and detector grid [4] has been done in the few years. Characters of the propagation of acoustic waves within the underwater atmosphere have caused several drawbacks with reference to the quality of presented physical routing clarification for underwater grid. There are 3 classes of routing protocols, specifically positive, immediate, and environmental routing protocols.

Positive protocols to determine routes for the primary time and every time the topology is changed due to quality, node failures or control state changes, as efficient topology info should be propagated to any or all interconnections devices, during this manner every device is in a position to determine a path to the other node in a very interconnections devices. Reactive protocols area unit a lot of applicable for dynamic environments however gain the

next latency thus for this reason these protocols aren't appropriate in UW_ASNs. Interconnections-layer protocols particularly designed for underwater acoustic grid area unit designed in some recent add [5], a routing protocol is designed that autonomously establishes the underwater configuration, controls interconnections resources, establishes interconnections flows, that build upon a national interconnections manager running on a surface location. In [6], the matter of information gathering three-dimensional underwater device grid tailored for long-run observation missions is investigated. The rule, however, doesn't think about applications with totally different needs. In [7], the authors examine the hold up-reliability deal-off for multi hop underwater acoustic grid. In [8], a long-run observation platform for underwater device grid contains of static and mobile nodes is designed, In [9], 3 versions of reliable unicast protocol area unit designed, that integrate Medium Access management (MAC) and routing functionalities and exploit totally different levels of neighbor knowledge: (i) no neighbor knowledge, (ii) one-hop neighbor knowledge, and (iii) two-hop neighbor knowledge.

III PROPOSED WORK

In this classification we discuss, a divided environmental routing solution for hold up insensitive and hold up sensitive underwater applications are introduced. For low bit error rate, envelope chain transmission scheme is used. So that we minimize the power consumption.

A. Approach Suitability and Envelope Chain

In view of this segment, we have a tendency to tend to review the impact of the character of the underwater surroundings on the acoustic approach utilization potency that is outlined because the internet bit rate doable on a link once considering envelope recommunication thanks to approach impairments, and supply tips for the look of routing clarification. once a continuing access technique could be utilize to transmit a knowledge envelope within the mutual acoustic standard (which act a general waterproof protocol utilized through the underwater acoustic unit residential by WHOI and Benet's), a trade-off between approach potency and link reliableness happens – in reality, whereas the previous will increase the latter decreases with the go up of the envelope size. equally, or routing clarification permit achieving 2 conflicting straights, i.e., increasing the potency of the acoustic approach by transmission a chain of small envelopes back-to-back; and warning the envelope error rate by maintenance the distance end to end of the transmitted envelopes small. In therefore the next, the envelope-chain idea to reinforce the approach potency and summarize the look philosophy to

line the best envelope size. whereas the best envelope size at the information link layer in associate underwater approach has been analytically derived in [10], The envelope improvement analysis in [10], in fact, doesn't think about the extra overhead caused by the utilize FEC theme, nor will it assess the amount of required envelope recommunication, that build upon the tough packet error rate (PER).

The payload of the information envelope to be transmitted is assumed to possess size L_P^D bits, whereas the header L_P^H bits. Moreover, the envelope could also be protected with a FEC mechanism that introduces a redundancy of L_P^F bits. Note that within the notation employed in the subsequent to represent variables and parameters, the subscripts and are related to envelopes and chains, severally. We have a tendency to decouple the result of the envelope size from the selection of the distance end to end of the chain, i.e., the amount of consecutive envelopes transmitted succeeding by a node: whereas the previous determines the envelope error rate, the latter will be exaggerated required so as to extend the approach potency.

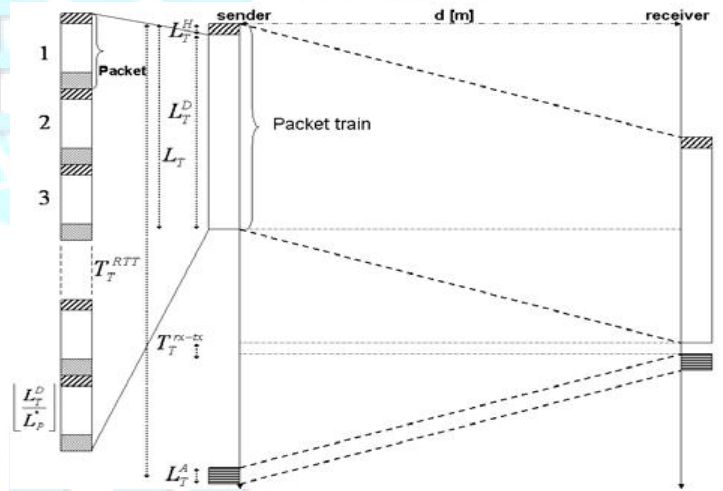


Fig1: envelope chain transmission scheme

In fact that the approach suitability associated with the envelope-chain scheme is,

$$\eta = \eta_T(L_T) \cdot \eta P(L_P, L_P^F). \quad (1)$$

$\eta_T(L_T)$ is the envelope-chain suitability, i.e., the ratio between the chain payload transmission time and the chain round-trip time (T_T^{RTT}) establish to the bit rate r ,

$$\eta_T(L_T) = L_T^D / (L_T^D + L_T^H + L_T^A + r \cdot (2d + T_T^{RX-TXT})) \quad (2)$$

where L_T^D , L_T^H and L_T^A are the chain, payload, header, and ACK distance end to end, T_T^{RX-TXT} is the time required to process the chain and control the circuitry as of getting to

put on air mode; $\eta_P (L_p, L_p^F)$ is the envelope suitability, i.e., the ratio of the envelope payload and the envelope size multiplied by the common number of communication N^{TX} such that an envelope effectively works out at the receiver,

$$\eta_P (L_p, L_p^F) = L_p - L_p^H - L_p^F / N^{TX} \cdot L_p \quad (3)$$

B. Delay insensitive Routing Algorithm

Hold up insensitive environmental routing algorithmic rule most previous environmental routing protocols assume that node will neither add a greedy mode or in an exceedingly recovery mode. Once in greedy mode, the node that presently grips the information tries to promote it towards the destination. Therefore the recovery mode is entered once a node fails to promote a information within therefore the greedy mode as none of its nearby resident may be a possible next hop. Typically this happens once the node - the alleged down node - view a void region between in itself and therefore the destination. Recovery mechanisms, which permit an envelope to be promoted to the destination once a down node is reached, area unit out of therefore the capacity of this effort. The protocol designed throughout this classification assumes that no void regions exist, though' it should be enhanced by combining it with one in every of the prevailing recovery mechanisms. The algorithmic rule tries to take advantage of those links that guarantee a coffee envelope error rate so as to maximize the likelihood that the envelope is correctly workout at the receiver. Used for these reasons, the power suitability of the link is weighted by the quantity of recommunication required to comprehend link reliableness, with the target of saving power.

P_{insen}^{dist} : Hold up insensitive Distributed Routing at Node I:

Given (offline): $L_p^*, L_p^H, E_{elec}^b, P_{i,max}^{TX}$

Computed (Online): $S_i, p_{is}^n, \wedge_{oj}$

Find: $j^* \in S_i \cap P_i^N, P_{ij}^{TX*} \in [0, P_{i,max}^{TX}] L P_{Pij}^{F*}$

Minimize : $E_i^{(j)} = E_{ij}^B \cdot L_p^* (L_p^* - L_p^H - L_p^F) \cdot N_{ij}^{TX} \cdot N_{ij}^{HOP} \quad (4)$

Subject To:

(Relationships)

$$E_{ij}^b = 2 \cdot E_{elec}^b + p_{ij}^{TX} / r; \quad (5)$$

$$L_{Pij}^F = \psi_{F-1}(L_p^*, PER_{ij}, \Phi^M(P_{ij}^{TX} / \wedge_{0j}, r, TL_{ij})); \quad (6)$$

$$N_{ij}^{TX} = 1 / (1 - PER_{ij}); N_{ij}^{HOP} = \max(d_{iN} / <d_{ij}> i_N, 1) \quad (7)$$

Where:

- $L_p^* = L_p^H + L_{Pij}^F + L_{Pij}^N$ [bit] is the fixed optimal envelopesize, where L_p^H is that the mounted header size of an envelope, whereas L_{Pij}^F is that the variable redundancy that's enclosed in every envelope transmit from node i to node j ; thus, $L_{Pij}^N = L_p^H + L_{Pij}^F + L_{Pij}^N$ is the variable payload size of each envelope transmit in a chain on link (i, j) .
- $E_{elec}^b = E_{elec}^{trans} = E_{elec}^{rec}$ [J/bit] in (5) is that the distance freelance power to transit one bit, wherever E_{elec}^{trans} is the power per bit required by receiver philosophy (PLLs, VCOs, bias currents, etc.) and therefore the E_{elec}^{rec} digital process, and represents the power per bit utilised by receiver
- $E_{ij}^b = 2 \cdot E_{elec}^b + P_{ij}^{TX} / r$ [J/bit] in (5) financial records for the power to transmit one bit from i to j , once the transmit power and therefore the bit rate are P_{ij}^{TX} [W] and r [bps], severally. The second term represents the distance-dependent classification of the ability mandatory to transmit slightly.
- N_{ij}^{TX} in (4) and (7) is that the common range of communication of an envelope sent by node i such that the envelope is properly work out at receiver j .
- $N_{ij}^{HOP} = \max(d_{iN} / <d_{ij}> i_N, 1)$. in (7) is that the calculable quantity of step from node i to the surface location (sink) N once j is chosen as next hop, wherever d_{ij} is that the distance between i and j , and $<d_{ij}> i_N$ (which we have a tendency to ask as advance) is that the projection of d_{ij} onto the road connecting node i with the sink.
- $BER_{ij} = \Phi^M(P_{ij}^{TX} / \wedge_{0j}, r, TL_{ij})$ in (6) represent the bit error worth on association (i, j) ; it's a utility of the magnitude relation between the power of the received little piece, $E_{rec}^b = P_{ij}^{TX} / (r \cdot TL_{ij})$, plus therefore the accepted noise at node j , \wedge_{0j} , and it build upon the utilize modulation theme \mathcal{M} .
- $LFP_{ij} = \psi_{F-1}(L_p^*, PER_{ij}, BER_{ij})$ in (6) returns the required FEC redundancy, given the best envelope size L_p^* , the envelope error rate and bit error worth on link (i, j) , and it ride the utilize FEC technique \mathcal{F} . Make a note of that, similarly, the envelope

error rate builds upon the FEC technique, the envelope distance end to end, the bit error rate, and therefore the FEC redundancy.

- S_i is that the neighbour set of node i , whereas \mathcal{P}^N_i is that the positive travel set, collected of nodes nearer to sink N than node i , i.e., $j \in \mathcal{P}^N_i$ if $d_{jN} < d_{iN}$.

C. Delay sensitive Routing Algorithm

The hold up sensitive routing algorithm allows each node to select in a distributed manner the optimal next hop, transmit power, and FEC envelope rate with the target of minimizing the power consumption. However, this algorithm takes in two new constraints to statistically get together the hold up sensitive application requirements:

- 1) The end-to-end envelope error rate ought to be less than an application-dependent threshold.
- 2) The chance that the end-to-end envelope hold-up be over a wait sure B_{max} , ought to be less than an application-dependent parameter.

P_{sen}^{dist} : Hold up sensitive Distributed Routing at Node i

Given (offline): $L_p^*, L_p^H, M = [L_T^* - L_T^H / L_p^*], E_{elec}^b, r, P_{i,max}^{TX}$

Computed (Online): $S_i, P_i^n, \wedge_{oj}, \Delta B_i^{(m)}, Q_{ij}$

Find: $j^* \in S_i \cap P_i^N, P_{ij}^{TX} \in [0, P_{i,max}^{TX}] LP_{ij}^{F*}$

Minimize: $E_i^{(j)} = E_{ij}^B \cdot L_p^* / L_p^H - LP_{ij}^{F*} \cdot N_{ij}^{HOP} \quad (8)$

Subject To:

(Relationships)

$$E_{ij}^b = 2 \cdot E_{elec}^b + (P_{ij}^{TX} / r); \quad (9)$$

$$LP_{ij}^F = \psi^{F-1}(LP^*, PER_{ij}, \Phi^M(P_{ij}^{TX} / \wedge_{oj}, r, TL_{ij})); \quad (10)$$

$$N_{ij}^{Hop} = \max(d_{iN} / < d_{ij} > i_N, 1); \quad (11)$$

(Constraint)

$$1 - (1 - PER_{ij})^{[N_{ij} Hop]} \leq PER_{max}^{e2e}; \quad (12)$$

The new notations utilized in the hold up sensitive difficulty generation are described as below:

- $M = [L_T^* - L_T^H / L_p^*]$, in is that the mounted range of envelopes transmitted during a chain on every link, wherever L_T and L_p are unit the optimum envelope size, severally.
- PER_{max}^{e2e} in (12) and $B_{max}[s]$ are the function-dependent end-to-end envelope error rate and hold up bound, respectively.
- $\Delta B_{(m)} = B_{max} - [t_{i,now}^{(m)} - t_0^{(m)}]$ [s] in is the time-to-exist of envelope m external at node i , where $t_{i,now}^{(m)}$ is the external time of mat i , and $t_0^{(m)}$ is the time m was generated, that is time-stamped within the envelope header by its supply.

The generation of P_{sen}^{dist} is quite parallel to P_{insen}^{dist} , except for 2 important changes:

- 1) Therefore the straight function (8) do not include N_{ij}^{TX} as no selective envelope retransmission is achieve.
- 2) New constraint is including (12) which address hold up sensitive application requirements.

The statistical assets of underwater links, personally want the chance we want the possibility that a envelope go over its end-to-end holdup sure to be less than an application-dependent mounted parameter. Hence, it ought to hold

$$\Pr\{[t_{i,now}^{(m)} - t_0^{(m)}] + B_{(j)}^{(i)} \geq B_{max}\} = \Pr\{B_{(j)}^{(i)} \geq \Delta^{(m)}_i\} \leq \gamma, \quad (13)$$

Where $B_{(j)}^{(i)}$ is that the expected hold up a envelope can increase from node i to the outside location N just the once j is chosen as next hop, and $\Delta^{(m)}_i = B_{max}[t_{i,now}^{(m)} - t_0^{(m)}]$ is that the time-to-exist of envelope m incoming at node i . Node i will estimate the remaining path hold up by projected for every potential next hop j , the calculable interconnections queuing hold up Q_{ij} and the transmission hold up T_{ij} to the remaining step N_{ij}^{Hop} , i.e.,

$$B_{(j)}^{(i)} \approx (T_{ij} + Q_{ij}) \cdot N_{ij}^{Hop} \quad (14)$$

Where

$$Q_{ij} = t_{i,now}^{(m)} - t_0^{(m)} - \sum_{(k,h) \in L_i}^{(m)} T_{kh} + Q_i + Q_j / N_{(m)}^{HC} + 2 \quad (15)$$

In (15), the estimated interconnections queuing hold up Q_{ij} is computed as the ratio of the sum of all the queuing hold ups knowledgeable by envelope m along its path $L_i^{(m)}$, which take in the links from the source generating envelope m to node i , and the common queuing hold ups Q_i , measured by node i , and Q_j , occasionally put on air by j ; and the number of nodes promoting the envelope, including node i , that build upon the hop count $N_{(m)}^{HC}$ (which is that the variety of step of envelope m from the source to the current node). This information is obtained by put on air

information's. However, to limit the transparency caused by these information, each node advertise its access hold up only when it exceeds a pre-defined entrance. Hence, this mechanism permits the routing rule to dynamically adjust to the ongoing traffic and the follow-on congestion.

IV. CONCLUSIONS

The difficulty of knowledge gathering throughout 3D underwater device interconnections was enquired by contemplating the interactions between the routing functions and thus the signal propagation character within the underwater atmosphere. 2 distributed environmental routing algorithms for hold up insensitive and hold up sensitive applications were presented and assessed through reflection; their straight is to satisfy the power consumption while taking the varying situation of the underwater acoustic approach and also the totally different application needs under consideration.

References

- [1] A. F. Harris III and M. Zorzi, "Energy- efficient routing protocol design considerations for underwater networks," in Proc. IEEE Conf. Sensor, Mesh Ad Hoc Commun. Netw. (SECON), San Diego, CA, June 2007.
- [2] J. Proakis, E. Sozer, J. Rice, and M. Stojanovic, "Shallow water acoustic networks," IEEE Commun. Mag., pp. 114-119, Nov. 2001.
- [3] M. Abolhasan, T. Wysocki, and E. Dutkiewicz, "A review of routing protocols for mobile ad hoc networks," Ad Hoc Netw. (Elsevier), vol. 2, pp. 1-22, Jan. 2004
- [4] K. Akkaya and M. Younis, "A survey on routing protocols for wireless sensor networks," Ad Hoc Netw. (Elsevier), vol. 3, no. 3, pp. 325-349, May 2005.
- [5] G. Xie and J. Gibson, "A network layer protocol for UANs to address propagation delay induced performance limitations," in Proc. MTS/IEEE Conf. Exhibition Ocean Eng., Science Technol. (OCEANS), vol. 4, Honolulu, HI, Nov. 2001, pp. 2087-2094.
- [6] D. Pompili, T. Melodia, and I. F. Akyildiz, "A resilient routing algorithm for long-term applications in underwater sensor networks," in Proc. Mediterranean Ad Hoc Netw. Workshop (Med-Hoc-Net), Lipari, Italy, June 2006.
- [7] W. Zhang and U. Mitra, "A delay-reliability analysis for multihop underwater acoustic communication," in Proc. ACM International Workshop UnderwaterNet. (WUWNet), Montreal, Quebec, Canada, Sep. 2007.
- [8] I. Vasilescu, K. Kotay, D. Rus, M. Dunbabin, and P. Corke, "Data collection, storage, and retrieval with an underwater sensor network," in ACM Conf. Embedded Netw. Sensor Syst. (SenSys), San Diego, CA, Nov. 2005.
- [9] A Nimbalkar and D. Pompili, "Reliability in underwater inter-vehicle communications," in Proc. ACM International Workshop UnderwaterNet. (WUWNet), San Francisco, CA, Sep. 2008.
- [10] M. Stojanovic, "Optimization of a data link protocol for an underwater acoustic channel," in Proc. MTS/IEEE Conf. Exhibition Ocean Eng., Science Technol. (OCEANS), Brest, France, June 2005.